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A Study on Anosov Diffeomorphisms on Real Bott Manifolds and Acyclic Digraphs

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Abstract

We provide a characterization of real Bott manifolds admitting Anosov diffeomorphisms in terms of acyclic digraphs.

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Keywords: Flat Riemannian manifold, Real Bott manifold, Acyclic digraph, Anosov diffeomorphism

1 Introduction

By the definition of [13], [14] a real Bott manifold is the total space B_n of a sequence of $\mathbb{R}P^1$ -bundles starting with a point:

$$B_n \to B_{n-1} \to \cdots \to B_2 \to B_1 \to \{a \text{ point}\}.$$

Each $\mathbb{R}P^1$ -bundle $B_i \to B_{i-1}$ is the projectivization of the Whitney sum of a real line bundle L_i and the trivial line bundle over B_{i-1} . Futhermore in [13], [14] it was explained that from the viewpoint of group actions, an *n*dimensional real Bott manifold (n-RBM) is the quotient of the *n*-dimensional torus $T^n = S^1 \times \cdots \times S^1$ by the product $(\mathbb{Z}_2)^n$ of cyclic group of order 2. The free action of $(\mathbb{Z}_2)^n$ on T^n can be expressed by an *n*-th upper triangular matrix A whose diagonal entries are 0 and the other entries are either 1 or 0. The orbit space $M(A) = T^n/(\mathbb{Z}_2)^n$ is the *n*-dimensional the real Bott manifold and we call A a *Bott matrix* of size n. The real Bott manifold M(A) also provides an example of a flat Riemannian manifold.

Let $f: M \to M$ be a diffeomorphism of a flat manifold M. We say f is an affine diffeomorphism of M if the lifting of f to universal covering \mathbb{R}^n of M belongs to $Aff(\mathbb{R}^n) = \mathbb{R}^n \rtimes GL(n, \mathbb{R})$ the group of affine transformation of \mathbb{R}^n . Such a lifting then automatically belongs to the normalizer $N_{Aff(\mathbb{R}^n)}(\pi)$ of the fundamental group $\pi = \pi_1(M)$ of M. An affine diffeomorphism f of M is hyperbolic if and only if f lifts to an affine transformation $(d, D) \in Aff(\mathbb{R}^n)$ with D hyperbolic (i.e. having no eigen-values of absolute value 1). As to the denition of Anosov diffeomorphism, you defined for any Riemannian metric df decomposes the tangent space into expansion-part and contraction-part. It had better mention that if df satises the Anosov property, then df satisfies for any Riemannian metric. So we take the euclidean metric (flat metric) on a flat manifold M to show that f is an Anosov diffeomorphism.

Note that each hyperbolic diffeomorphism of a flat Riemannian manifold M defines an Anosov diffeomorphism on M. Conversely, K. Dekimpe et al. [6] proved the following lemma.

Lemma 1.1 ([6]). If $f: M \to M$ is an Anosov diffeomorphism of a flat Riemannian manifold M, then f is homotopic to a hyperbolic diffeomorphism $g: M \to M$.

Recall that if π is any crystallographic group, then π satisfies an exact sequence

$$0 \to \Lambda \to \pi \to \Phi \to 1$$

where $\Lambda = \pi \cap \mathbb{R}^n$ is a lattice of rank n, and $\Phi = p_r(\pi)$ is a finite group. Here $p_r \colon \mathcal{E}(n) \to \mathcal{O}(n)$ is a homomorphism defined by $p_r(d, D) = D$, $(d, D) \in \mathcal{E}(n)$. We call Φ , the holonomy group of π (see [7]).

Flat Riemannian manifolds supporting Anosov diffeomorphisms can be characterized by the following theorem:

Theorem 1.2 ([5]). An *n*-dimensional flat manifold M with holonomy group Fand associated holonomy representation $T: F \to GL(n, \mathbb{Z})$ admits an Anosov diffeomorphism if and only if each \mathbb{Q} -irreducible component of T of multiplicity one is reducible over \mathbb{R} .

Here, "multiplicity" means the number of times a component appears in the decomposition of T.

In [13] it was introduced three operations, which are called moves, to a Bott matrix A under which the diffeomorphism class of M(A) does not change. By an iteration of the moves, M(A) is diffeomorphic to $T^k \times_{(\mathbb{Z}_2)^s} M(B)$. That is, there is a k-torus action on M(A) whose quotient space is an (n - k)-dimensional real Bott orbifold $M(B)/(\mathbb{Z}_2)^s$ by some $(\mathbb{Z}_2)^s$ -action $(1 \le s \le k)$.

Here M(B) is an (n - k)-dimensional real Bott manifold corresponding to a Bott matrix B of size (n - k). In addition, each of such M(A) has the first Betti number $b_1(M(A)) = k$, $1 \le k \le n$. This result also implies that the Bott matrix A reduces to

$$\left(\begin{array}{c|c|c} O_{k-s} & 0 & 0\\ \hline 0 & O_s & *\\ \hline 0 & 0 & B \end{array}\right).$$
(1)

It follows that

$$M(A) = T^n / (\mathbb{Z}_2)^n = \mathbb{R}^n / \pi(A).$$

Here $\pi(A)$ is the fundamental group of M(A).

On the other hand, an n-RBM is a small cover over an n-cube (see [10]). (See definition of a small cover in [8].) Choi [9] showed that small covers over cubes are strongly related to acyclic digraphs. If D is an acyclic digraph then its adjacency matrix A_D with respect to its acyclic ordering (i.e., if (v_i, v_j) is an arc in D then i < j) is an upper triangular matrix with zero diagonals. Choi and Oum [10] introduced two operations, the so-called local complementation and slide, on acyclic digraphs and proved that two acyclic digraphs D and H are Bott equivalent (i.e., one has an isomorphic digraph that is obtained from the other by successively applying the two operations) if and only if the corresponding real Bott manifolds $M(A_D)$ and $M(A_H)$ are diffeomorphic.

In this paper we provide the characterization of real Bott manifolds admitting Anosov diffeomorphisms in terms of acyclic digraphs.

2 Bott equivalence of acyclic digraphs

In this section we review the terminology in graph theory, and recall two operations on acyclic digraphs and some results in [10].

A directed graph (or just digraph) D = (V, E) consists of a non-empty finite set V := V(D) of elements called vertices and a finite set E := E(D)of ordered pairs e = (u, v) of distinct vertices called arcs. We call V(D) the vertex set and E(D) the arc set of D. The order of D (denoted by |D|) is the number of vertices in D. An ordering v_1, v_2, \ldots, v_n of vertices of a digraph Dis an acyclic ordering if i < j for each arc (v_i, v_j) in D. A digraph is acyclic if it admits an acyclic ordering.

If (u, v) is an arc of D, we say that a vertex u is *adjacent* to a vertex v in D, v is called an *out-neighbor* of u and u is called an *in-neighbor* of v. For a vertex $v \in D$, we use the following notation:

$$N_D^+(v) = \{ u \in V \setminus \{v\} | (v, u) \in E \}, \ N_D^-(v) = \{ u \in V \setminus \{v\} | (u, v) \in E \}.$$

 $deg_D^+(v) = |N_D^+(v)|$ is the number of out-neighbors of v, and $deg_D^-(v) = |N_D^-(v)|$ is the number of in-neighbors of v.

For two graphs D = (V, E) and D' = (V', E'), a bijection $f: V \to V'$ is called an *isomorphism* when $(u, v) \in E$ if and only if $(f(u), f(v)) \in E'$. Two digraphs are *isomorphic* if there is an isomorphism.

For a graph D = (V, E) with a fixed ordering $\{v_1, v_2, \ldots, v_n\}$ of V, the adjacency matrix of D is an $n \times n$ matrix $A_D = (a_{ij})_{i,j \in 1,2,\ldots,n}$ such that

$$a_{ij} = \begin{cases} 1 & \text{if } (v_i, v_j) \in E, \\ 0 & \text{otherwise.} \end{cases}$$

An acyclic digraph H is *Bott equivalent* to an acyclic digraph D if H has an isomorphic digraph that is obtained from D by successively applying *local complementations* and *slides*. In the following, Choi and Oum[10] introduced local complementations and slides.

For a vertex v of a digraph D, let D * v be a digraph obtained by adding an arc (u, w) if $(u, w) \notin E$, or removing the arc (u, w) otherwise, for each pair $(u, w) \in N_D^-(v) \times N_D^+(v)$ with $u \neq w$. This operation to obtain D * v from Dis called a *local complementation* at v. A local complementation on digraphs was first introduced by Bouchet[1].

For two sets X and Y, we write $X \triangle Y = (X \setminus Y) \cup (Y \setminus X)$. For two distinct vertices v, w having the same set of in-neighbors in a digraph D, we define $D \triangle vw$ to be a digraph obtained by replacing $N_D^+(w)$ with $N_D^+(w) \triangle N_D^+(v)$. This operation to obtain $D \triangle vw$ from D is called a *slide*.

It is easy to observe that if D is an acyclic digraph, then so are D * v and $D \triangle xy$ (assuming $N_D^-(x) = N_D^-(y)$).

If D is an acyclic digraph, then its adjacency matrix A_D with respect to its acyclic ordering is an upper-triangular square matrix with zero diagonals, i.e, A_D is a Bott matrix. So, there is a bijection from the set of Bott matrices of size n to the set of acyclic digraphs on vertices $\{v_1, \ldots, v_n\}$. Therefore we can study real Bott manifolds in terms of acyclic digraphs.

Theorem 2.1 ([10], Theorem 4.4). Two acyclic digraphs D and H are Bott equivalent if and only if the corresponding real Bott manifolds $M(A_D)$ and $M(A_H)$ are diffeomorphic.

3 Anosov diffeomorphisms on real Bott manifolds and acyclic digraphs

In this section, we study the relation between an Anosov diffeomorphism of a real Bott manifold M(A) and an acyclic digraph D corresponding to a Bott matrix A as the adjacency matrix of D.

Given an n-RBM $M(A) = T^k \times_{(\mathbb{Z}_2)^s} M(B)$. Let $\{v_1, \ldots, v_n\}$ be the set of vertices of an acyclic diagraph D corresponding to the adjacency matrix A.

By definition, if an entry $a_{ij} = 1$ in A then there is an arc $(v_i, v_j) \in E(D)$. This means, $v_i \in N_D^-(v_j)$ and $v_j \in N_D^+(v_i)$.

Since each Bott matrix A can be reduced to (1), $N_D^-(v_i) = \emptyset$ for i = 1, ..., kand $N_D^-(v_j) \neq \emptyset$ for j = k + 1, ..., n. Note that $\{v_{k+1}, ..., v_n\}$ is the set of vertices of an acyclic diagraph H corresponding to the adjacency matrix B.

Theorem 3.1. Given a real Bott manifold M(A), and let D be the acyclic digraph corresponding to the adjacency matrix A. M(A) supports an Anosov diffeomorphism if and only if for each $v \in V(D)$ there is a $w \in V(D)$ ($v \neq w$) such that $N_D^-(v) = N_D^-(w)$.

Proof. Let F be the holonomy group of M(A) and $T: F \to GL(n, \mathbb{Z})$ be the associated holonomy representation. It is easy to see that the holonomy representation T of M(A) has the diagonal form:

$$T(x) = \begin{pmatrix} I_k & 0 \\ & \hat{1} & \\ 0 & \ddots & \\ & & \hat{1} \end{pmatrix}, \quad \forall x \in F, \quad \hat{1} \in \{1, -1\}.$$

The diagonal entries of T(x) correspond to the entries in a row of A where the entries 1 and -1 in T(x) correspond to 0 and 1 respectively in a row of A. By Maschke's theorem[11], since F is finite, the holonomy representation T is completely reducible over \mathbb{Q} and so T decomposes as a direct sum of \mathbb{Q} -irreducible components:

$$T(x) = T_1(x) \oplus \dots \oplus T_n(x) \quad \forall x \in F,$$

$$T_i(x) \in \{1, -1\} \quad \forall i = 1, \dots, n.$$

So each \mathbb{Q} -irreducible component T_i of T has dimension one. Obviously, such components are not reducible over \mathbb{R} . By definition, T_i is equivalent to T_j $(T_i \sim T_j, i \neq j)$, if there exists $m \in GL(1,\mathbb{Z})$ such that $mT_i(x) = T_j(x)m$, $\forall x \in F$.

 (\Rightarrow) Assume that M(A) admits an Anosov diffeomorphism. Since each \mathbb{Q} irreducible component T_i is not reducible over \mathbb{R} , by Theorem 1.2, there is
no \mathbb{Q} -irreducible component of T of multiplicity one (i.e., each 1-dimensional \mathbb{Q} -irreducible component of T has at least multiplicity two). Hence for each T_i , there is T_j $(i \neq j)$ such that $T_i \sim T_j$ (i.e., for each column x of A, there is
a column y such that x = y). So, in terms of the acyclic digraph D, for each $v \in V(D)$ there is $w \in V(D)$ such that $N_D^-(v) = N_D^-(w)$.

(\Leftarrow) Assume that M(A) does not support an Anosov diffeomorphism. Again by Theorem 1.2, there is a Q-irreducible component of multiplicity one which is not reducible over \mathbb{R} . Since each Q-irreducible component T_i is not reducible over \mathbb{R} , there is $v \in V(D)$ such that $N_D^-(v) \neq N_D^-(w)$ for any $w \in V(D)$. So we have a contradiction. Ishida [4] proved that an n-RBM M(A) is symplectic if and only if $|\{k|N_D^-(v_k) = N_D^-(v_j)\}|$ is even for every $j \in \{1, \ldots, n\}$, with $V(D) = \{v_1, \ldots, v_n\}$. This means each symplectic real Bott manifold admits an Anosov diffeomorphism.

Corollary 3.2. If a real Bott manifold M(A) admits an Anosov diffeomorphism then

- a) The source of D is not unique.
- b) For every pair $\{v, w\} \subset V(D), |N_D^+(v) \cap N_D^+(w)| \neq 1.$
- c) For every pair $\{v, w\} \subset V(D), |N_D^+(v) \setminus \{N_D^+(v) \cap N_D^+(w)\}| \neq 1$ and $|N_D^+(w) \setminus \{N_D^+(v) \cap N_D^+(w)\}| \neq 1.$
- d) For each $v_j \in V(D)$, $|N_D^+(v_j) \setminus \{\bigcup_{\substack{i=1 \ i \neq j}}^n N_D^+(v_i)\}| \neq 1$.

Proof. Recall that $v \in V(D)$ is a source of D if $deg_D^-(v) = 0$. If the source of D is unique, then the corresponding M(A) admits a maximal S^1 -action (i.e., $b_1(M(A)) = 1$). Hence M(A) does not admit an Anosov diffeomorphism ([5]). For b), assume that there exists a pair $\{v, w\} \in V(D)$ such that $|N_D^+(v) \cap N_D^+(w)| = 1$. Let $u \in N_D^+(v) \cap N_D^+(w)$. Then $N_D^-(u) \neq N_D^-(x)$ for any $x \in V(D)$. We have a contradiction. For c) and d, the proofs are similar to b). \Box

Since each Bott matrix A can be reduced to (1), as a consequence we obtain the following corollary.

Corollary 3.3. If an n-RBM $M(A) = T^k \times_{(\mathbb{Z}_2)^s} M(B)$ admits an Anosov diffeomorphism then the (n - k)-dimensional real Bott manifold M(B) also admits an Anosov diffeomorphism.

This corollary coinsides with Nazra's result (Theorem 2.1 in [3]) which is proved by using topological method.

In order to determine the number of distinct diffeomorphism classes of M(A) supporting Anosov diffeomorphisms, we can apply Theorem 3.1 together with Theorem 2.1.

Example 3.1. Here we give an example that if a real Bott manifold M(B) admits an Anosov diffeomorphism then a real Bott manifold $M(A) = T^k \times_{(\mathbb{Z}_2)^s} M(B)$ obtained from M(B) by $(\mathbb{Z}_2)^s$ -action does not necessarily admit an Anosov diffeomorphism.

Consider the 2-dimensional torus T^2 . The corresponding Bott matrix is $B = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$. It is well known that every diffeomorphism on T^n $(n \ge 2)$ admits an Anosov diffeomorphism ([12]). Now we obtain a 4-dimensional real Bott manifold M(A) with $(\mathbb{Z}_2)^2$ -action on M(B) where the corresponding Bott matrix $A = \begin{pmatrix} 0 & 0 & | & 0 & 1 \\ 0 & 0 & | & 0 & 1 \\ 0 & 0 & | & 0 & 0 \\ 0 & 0 & | & 0 & 0 \end{pmatrix}$. By The-

orem 3.1, it is clear that M(A) does not admit an Anosov diffeomorphism.

4 Conclusion

Related to the acyclic digraph which correspond to a real Bott manifold, we obtain necessary and sufficient conditions for the real Bott manifold to admit an Anosov diffeomorphism.

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