Machining Simulation of AISI 1045 and Carbide Tool Using FEM

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ABSTRACT

In recent years, the applications of finite element method (FEM) in metal cutting operations have proved to be effective in studying the cutting process and chip formation. In particular, the simulation results can be used for both researchers and machine tool makers to optimize the cutting process and designing new tools. Many researches were done on two-dimensional simulation of cutting process because the three-dimensional versions of FEM software required more computational time. The present work aims to simulate three-dimensional orthogonal cutting operations using FEM software of Deform-3D. Orthogonal cutting speed on effective-stress, strain and temperature in turning process. AISI 1045 was used as work material and cutting tool was TNMA 332 (uncoated carbide tool, SCEA = 0; BR = -5; SR = -5 and radius angle 60°). The emphasis on the designed geometries are limited to the changes in the cutting speed between 100 m/min and 450 m/min. The machining parameters of feed rate and depth of cut were kept constant at 0.35 mm/rev and 0.3 mm respectively.

The simulation results show that by increasing the cutting speed causes a decrease in cutting force and effective-strain. On the other hand, increasing in cutting speed will increase effective -strain and temperature of the chip formed.

Key Words: finite element method, three-dimensional of orthogonal cutting, AISI 1045, carbide tool

INTRODUCTION

Finite Element Analysis (FEA) technique was the first introduced in 1960s and has been widely used to analyze in designing tools and forming processes. Based on the success of FEM simulations for bulk forming processes, many researchers developed their own FEM codes to analyze metal cutting processes during the early 1980s up to now (Marusich, et all, 1995; Cerenitti et al, 1996; Xie et all, 1998; Shet et all, 2000). Cerenitti (1996) assumed a rigid sharp tool and elastoplastic workpiece, and defined a node separation criterion based on the geometry of the element approaching the cutting edge. Cerenitti (1996) used an early version of a commercial implicit FEM code "DEFORM-2DTM". This code uses four-node quadrilateral elements and is based on static Lagrangian formulation. Today, DEFORM-3DTM code is commonly used by researchers and industry in

machining simulation (Columbus, 2007). Applications of FEM models for machining can be divided into six groups: 1) tool edge design, 2) tool wear, 3) tool coating, 4) chip flow, 5) burr formation and 6) residual stress and surface integrity. The direct experimental approach to study machining processes is expensive and time consuming. For solving this problem, the finite element methods are most frequently used. Modeling tool wear using FEM has advantages over conventional statistical approach because it requires less experimental effort and it provides useful information such as deformations, stresses, strain and temperature in chip and the work piece, as well as the cutting force, tool stress and temperature on the tool working under specific cutting parameter. (Mackerle, 1999)

METHODOLOGY

This paper presents the application of Deform-3D in simulation orthogonal cutting process of AISI 1045 and carbide tool at various cutting speeds while the other machining parameters of feed rate and depth of cut were kept constant. The commercial software Deform-3D for deformation analysis was used to simulate orthogonal metal cutting process. It is based on an updated Lagrangian formulation and employs an implicit integration scheme. Figure 1 shows Geometry and Schematic of orthogonal cutting condition model.

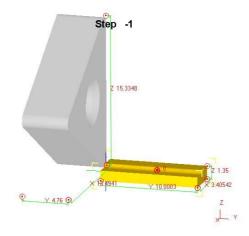


Figure 2 Geometry and Schematic of orthogonal cutting condition model

The workpiece material was an AISI 1045 carbon steel. AISI 1045 carbon steel had been selected as the workpiece material in this study because it was well characterized and had been the focus of many recent modelling studies. Table. 1 show flow stress models for AISI-1045 carbon steel used in the simulation.

The tool is modeled as a rigid body, so there are no mechanical properties need to be assigned and only thermal properties are needed. The mechanical properties of AISI 1045 steel and carbide cutting tool are shown in Table 3. The tool was defined to be a rigid body which considers thermal transfer for modeling the cutting temperature field.

Deform software had been used to simulate the effect of cutting speed on the parameter of machining when turning AISI 1045 using uncoated carbide cutting tool. The simulations were performed by changing the cutting speed while the feet rate and depth of cut were kept constant at 0.35 mm/rev and 0.3 mm respectively as shown in Table 2. The simulation results of cutting force, effective-stress, strain and chip temperature on the cutting were studied and analyzed. The operation is simulated using a nose angle 60° and without used of coolant.

The three-dimensional finite element model was generated under a plane strain assumption because the width of cut was larger than the undeformed chip thickness in this orthogonal cutting arrangement. The flow stress behavior of the work material and the contact conditions, physical and thermomechanical properties of the workpiece and tool materials, and cutting conditions are predefined and input to the simulation model as listed in Table 3.

| Material Model | Equation for flow stress σ models | Material constants | Variables |
|-----------------------------------|--|------------------------------|-----------|
| Oxley (1989) | $\sigma = \sigma_1 \varepsilon^n$ | $\sigma_{1,n} = f(T_{mod})$ | ε, έ, Τ |
| Maekawa et al. (1983) | $\sigma = \mathbf{B}\left(\frac{\dot{\varepsilon}}{1000}\right)^{\mathrm{M}} \mathrm{e}^{\mathrm{aT}}\left(\frac{\dot{\varepsilon}}{1000}\right)^{\mathrm{m}} \left[\int \mathrm{e}_{-\frac{-dT/N}{\mathrm{strain path}}}\left(\frac{\dot{\varepsilon}}{1000}\right)^{-\mathrm{m'N}} d\varepsilon\right]^{\mathrm{V}}$ | B,N = f(T)M,m,a | ε, έ, Τ |
| Zerilli and Amstrong (1987) | $\sigma = C_0 + C_1 + \exp(-C_3 T + C_4 T \ln \dot{\epsilon}^*) + C_2 \epsilon^n$ | $C_0, C_1, C_2, C_3, C_4, n$ | ε, έ, Τ |
| Johnson and Cook (1983) | $\sigma = (\mathbf{A} + \mathbf{B}\varepsilon^n)(1 + \mathbf{C} \ln \varepsilon^*)(1 - \mathbf{T}^{*m})$ | A,B,C,m,n | ε, έ, Τ |
| El-Magd et al. (2003) | $\sigma = f(\sigma_{o,} \acute{\epsilon}), \sigma_{o} = f(\epsilon, \acute{\epsilon}, T)$ $\Delta \sigma_{\text{steel} - CK45} = f(T, \acute{\epsilon}), \sigma_{\text{steel}} = \sigma + \sigma_{\text{steel} - CK45}$ | é [*] ,m,n | ε, έ, Τ |

Table 1Flow stress models for AISI-1045 carbon steel

TABLE 2 Input Parameters in the simulation process

| Parameters | | | | | | | | | | |
|-----------------|-----|-----|-----|-----|-----|--------|---------|------------|-------|--|
| Cutting Speed | 100 | 150 | 200 | 250 | 300 | 350 | 400 | 450 | | |
| (m/min) | | | | | | | | | | |
| Feed Rate | | | | | | Kept c | onstant | at 0.35 mm | n/rev | |
| Depth of cut | | | | | | Kept c | onstant | at 0.3 mm | | |
| Nose Angle (°C) | | | | | | Kept c | onstant | at 60 °C | | |

Table 3 Cutting condition to the simulation models

| Tool Geometry of TNMA 332 (WC as | base ma | terial, u | incoated | l carbide | e tool) | | | | |
|---|-----------|-----------|----------|-----------|---------|-----|-----|-----|------|
| Side Cutting Edge Angle (SCEA) | 0 | , | | | | | | | |
| Back Rake Angle (deg) | -5 | | | | | | | | |
| Side Rake Angle (deg) | -5 | | | | | | | | |
| Nose Angle (°C) | 0.6 | | | | | | | | |
| Tool properties (uncoated carbide; Poi | sson's ra | tio. 0.2 | 2) | | | | | | |
| Modulus Young (GPa) | 500 | | _/ | | | | | | |
| Modulus of Elasticity (Gpa) | 641 | | | | | | | | |
| Poison Ratio | 0.26 | | | | | | | | |
| | | | | | | | | | |
| Boundary Condition | | | | | | | | | |
| Initial Temperature (°C) | 20 | | | | | | | | |
| Shear friction factor | 0,5 | | | | | | | | |
| Heat transfer coefficient at the | 45 | | | | | | | | |
| workpiece tool interface (N/s mm°C) | | | | | | | | | |
| Work peace geometry | | | | | | | | | |
| Depth of cut | 0,3 | | | | | | | | |
| Width of cut (mm) | 3,4 | | | | | | | | |
| Length of workpeace | 10 | | | | | | | | |
| Workpiece properties (AISI 1045; Pois | sson's ra | tio, 0.30 |)) | | | | | | |
| Modulus of elasticity [37] (GPa) | 215 | 210 | 165 | 160 | | | | | |
| at temperature ($^{\circ}C$) | 20 | 200 | 400 | 600 | | | | | |
| Thermal expansion [38] $(\cdot 10^5 \text{ °C}^{-1})$ | 1.1 | 1.2 | 1.3 | 1.4 | 1.4 | 1.5 | 1.5 | | |
| at temperature (°C) | 100 | 200 | 300 | 400 | 500 | 600 | 700 | | |
| Heat capacity [39] (N/mm2 ° C) | 3.7 | 3.8 | 4.3 | 5.1 | 8.8 | 8.3 | 7.5 | 6 | 5.64 |
| at temperature (°C) | 25 | 125 | 325 | 525 | 725 | 825 | 875 | 925 | 975 |
| Thermal conductivity [39] (W/m °C) | 42 | 43 | 38 | 35 | 29 | 28 | 24 | 23 | 23 |
| at temperature (°C) | 25 | 100 | 300 | 500 | 700 | 800 | 900 | 950 | 1000 |

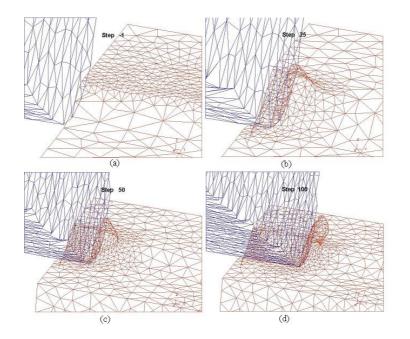


Figure 2 (a) Initial mesh and tool indentation, (b) Chip formation at step 25,

(c) Chip formation at step 50, (d) Developed continues chip at step 100.

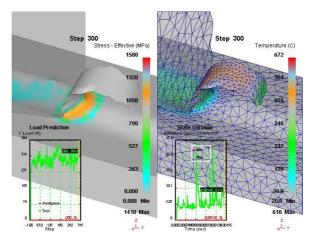


Figure 3 Example of the simulation result for cutting speed at 200 m/min (for running in 300 step)

Displacement, shape and surface mesh of tool and workpiece at initial mesh in the beginning of the cutting operation until the developed chip formation at step 100 as illustrated in Figure 2 a , 2b, 2c and 2d respectively The workpiece and the tool are characteristized by non uniform mesh distribution in the simulation. Very small element is required in the contact area between tool and workpiece because of very large temperature gradient and stress that will develop in this region during the simulation. Figure 3 shows an example of simulation result for cutting speed 100 m/min that was found from 300 steps of simulation running and needs longer time simulation.

RESULT AND DISCUSSION

Detailed Study of FEM Simulation

Figure 4a shows the simulation result for displacement. The longer the chip generated caused higher mesh displacement found as at the end of chip formed. The biggest deformation was occurred on the primary deformation zone, followed by the secondary deformation zone. This also cause higher stress occurred in this section. This result is agreeable with Kalhori (2001) where the major deformation during cutting process were concentrated in two region close to the cutting tool edge, and the bigger deformation were occurred in the primary deformation zone, followed by secondary deformation zone, sliding region and sticking region as shown in Figure 4b.

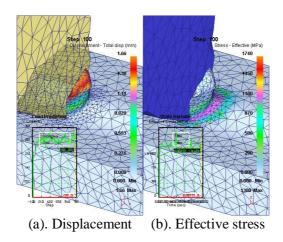


Figure 4 The simulation result for (a) displacement, cutting speed, (b). Stress and strain at 100 m/min (step 100)

Stress and temperature can be analyzed in detail based on its contour, this will give the value of stress and temperature for each of lines or points in all region of workpiece and chip formed as shown in Figure 5 and Figure 6.

Figure 5 shows that on the primary deformation zone, higher deformation is experienced, which resulted in higher stress It can be seen the contour of stress where higher at line of H (1520 MPa) and G (1300 MPa).

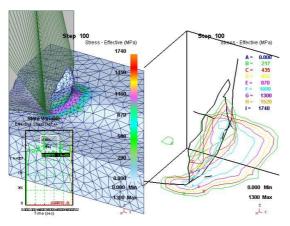


Figure 5 The simulation result for stress contour at 100 m/min (Step 100)

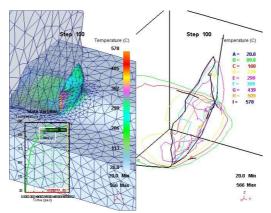


Figure 6 The simulation result for temperature contour at 100 m/min (Step 100)

In the sticking region, the work piece material adheres to the tool and shear occurs within the chip, the frictional force is high and consequently is generated. Therefore, the highest temperature in the chip usually occurs in the sliding region. Figure 6 shows contour of temperature generated in each region, and higher temperatures are around at line of G (439°C) and H (509°C) on sliding region.

Figure 7 shows the cutting force that generated during the cutting simulation, the cutting force remained constant (fluctuation on horizontal direction) after step 20, the same phenomenon is also observed in the gradient temperature, it remained constant after Step 42. Bigger fluctuation are found in effective-strain, therefore more difficult to predict the strain value compared to predict the effective-stress as given in Figure 8.

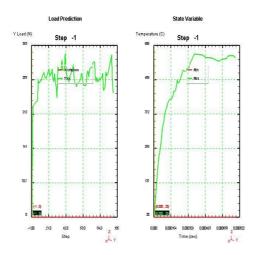


Figure 7 The graph result of simulation for cutting force and temperature contour for cutting speed 100 m/min (step 100)

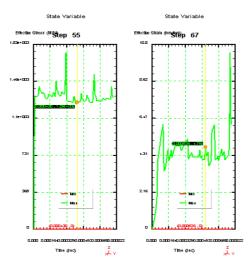


Figure 8 The graph result of simulation for cutting effective-stress and strain for cutting speed 100 m/min (step 100)

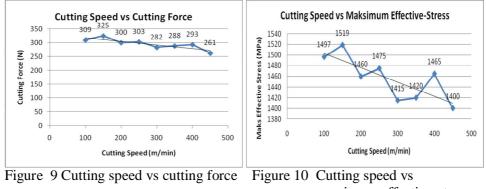
Effect of Increasing of Cutting Speed on Machining Result

The cutting force, effective stress, strains and chip temperature at various cutting speed were studied and analyzed as shown in Table 4. The maximum and minimum value of each cutting parameter for cutting force, effective-stress, effective-strain and generated chip temperature in this simulation were plotted in Figure 9, Figure 10, Figure 11 and Figure 12 respectively.

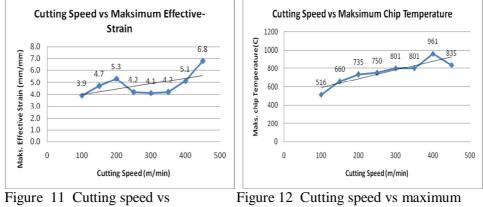
In Table 4, the simulation for cutting speed were done for 100 m/s - 450 m/min.

| No | Cut. Speed (m/min) | Depth of cut (mm) | Feed (mm/ tooth) | Min Force (N) | Max Force (N) | Av. Force (N) | Min Eff. Stress (MPa) | Max. Eff Stress (MPa) | Av. Eff. Stress (MPa) | Av. Strain (mm/ mm) | Min Temp (C) | Max Temp (C) | Av. Tem p (C) |
|----|--------------------------|-------------------------|------------------------|---------------------|---------------------|---------------------|--------------------------------|--------------------------------|--------------------------------|------------------------------|--------------------|--------------------|-------------------------|
| 1 | 100 | 0,3 | 0,35 | 281 | 337 | 309 | 1253 | 1740 | 1497 | 3.9 | 553 | 478 | 516 |
| 2 | 150 | 0,3 | 0,35 | 249 | 400 | 325 | 1260 | 1778 | 1519 | 4.7 | 644 | 675 | 660 |
| 3 | 200 | 0,3 | 0,35 | 255 | 344 | 300 | 1330 | 1590 | 1460 | 5.3 | 707 | 763 | 735 |
| 4 | 250 | 0,3 | 0,35 | 256 | 349 | 303 | 1270 | 1680 | 1475 | 4.2 | 723 | 777 | 750 |
| 5 | 300 | 0,3 | 0,35 | 256 | 308 | 282 | 1400 | 1430 | 1415 | 4.1 | 780 | 821 | 801 |
| 6 | 350 | 0,3 | 0,35 | 250 | 325 | 288 | 1290 | 1550 | 1420 | 4.2 | 731 | 870 | 801 |
| 7 | 400 | 0,3 | 0,35 | 249 | 336 | 293 | 1300 | 1630 | 1465 | 5.1 | 937 | 984 | 961 |
| 8 | 450 | 0,3 | 0,35 | 250 | 272 | 261 | 1350 | 1450 | 1400 | 6.8 | 821 | 849 | 835 |

Table 4The cutting force, effective stress, strain and chip temperature at
various cutting speed were studied and analyzed.



maximum effective-stress



chip temperature

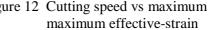


Figure 9 shows that by the increasing of the cutting speed, it will decrease the cutting force. This is agreeable with theory that by the increasing of cutting speed will soften the material, therefore this will make material easier to cut in higher cutting speed condition.

Figure 10 shows that by increasing the cutting speed also will reduce the effective-stress. This is also agreeable with theory and Cerenitty. Et all (1996) an other research. The good result were get for the graph of temperature where the increasing of cutting speed will increase the generated temperature on chip as given in Figure 12. This is agree with Cerenitti. et all (1996) where the maximum temperature of chip are increasing with increasing cutting speed.

Based on theory, the graph of effective-strain should remain constant, but in this simulation, as given in Figure 11, the increasing cutting speed cause a sligh increase effective-strain, this was caused by difficulty in getting the average of effective-strain value, because there were high fluctuation in resulted graphs.

CONCLUSION

The distribution of cutting force, effective stress and temperature obtained from simulations are in good agreement with the result given in literature.

From simulation, there can be concluded that by increasing of the cutting speed in turning of AISI 1045 using Tungsten Carbide (CW) will decreasing of cutting force and effective stress. In the different case, increasing of cutting speed cause increasing of generated temperature on chip.

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